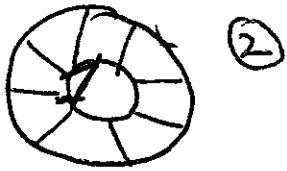


f.) Spherical Geometry

a.) Motivation:

→ $R = R(t)$, etc. \Leftrightarrow effects of imploding system, convergence etc.

→ Multiple Surfaces:



3 stages of R.T. instability:

a.) acceleration phase: - ablated material accelerated into shell \Rightarrow R.T. instability at (2)

$R = 3\text{mm} \rightarrow 1.5\text{mm}$

b.) coasting phase: - shell coasts inward with no acceleration \rightarrow ballistic \Leftrightarrow no acceleration \Rightarrow no R.T.

$R = 1.5\text{mm} \rightarrow 150\mu$

c.) deceleration phase: - shell decelerates, compresses gaseous core (gas igniter) \Rightarrow R.T. instability at (1) (eff outward)

$R = 150\mu \rightarrow 75\mu$

1 → inner

2 → outer

89.

Impact on ICF design:

- naively, coating phase appears benign, as no R.T. instability
- but a.) during acceleration, early coating shell radius thin

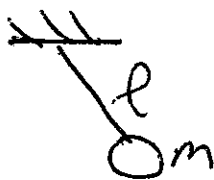
$$b.) \quad \varphi|_{R_1} = \exp\left[-\frac{l}{R_1} (R_2 - R_1)\right]$$

⇒ outer surface R.T. seeds inner surface perturbation

⇒ inner surface perturbation grows due convergence prior to deceleration

- examples:

a.) Pendulum



with $l = l(t)$

$$\dot{l}/l \ll \omega = \sqrt{g/l}$$

Adiabatic invariant \leftrightarrow action

$$S = \int p dq = \int p_\theta d\theta ; \text{ here}$$

$$H = \frac{p_0^2}{2mL^2} + \frac{1}{2} mgL\omega^2 \Rightarrow p_0(\omega), S' \text{ etc.}$$

Alternatively: $S' = \text{Action}$
 $\sim \text{Energy} \times \text{time}$

$$S' = \left(\frac{1}{2} mgL A^2 \right) (\omega^{-1})$$

$$= \frac{1}{2} m g L^2 A^2 \omega^{-1}$$

$$= \frac{1}{2} m \omega L^2 A^2$$

$$\therefore S' \sim m L^{3/2} \sqrt{g} A^2$$

$$\Rightarrow L_0^{3/2} A_0^2 = L(t)^{3/2} A(t)^2$$

$$A(t)/A_0 = (L_0/L(t))^{3/4}$$

i.e. shortening string increases amplitude!

b.) Ocean Wave Impinging on Beach



Now, $\omega = \omega(k, g, d(x))$ for finite depth

'y analogy with pendulum:

Action Density (Wave) $N = \mathcal{E}/\omega$

\mathcal{E} = wave energy density

[aside: QM: $E = (N + 1/2) \hbar \omega$
 \downarrow
 # quanta

Semiclassical: $E = N \hbar \omega$

Classical: $\hbar \rightarrow 1$ $\Rightarrow N = \mathcal{E}/\omega$
 $N \rightarrow$ action

Then: - action density (= # waves) conserved along wave trajectories

$$-\frac{\partial}{\partial t} N + \nabla \cdot (V_{gr} N) = 0$$

$$\rightarrow V_{gr}(d(x)) \frac{\mathcal{E}(x)}{\omega(d(x))} = \text{const}$$

- Key Point:

- during coasting phase, inner surface is RT stable but, inner surface

- supports surface waves, seeded by outer surface RT perturbations
- as surface wave ~ harmonic oscillator can expect growth as R shrinks during coasting

<u>c.e.</u>	<u>Pendulum</u> $\omega = \sqrt{g/L}$ m	<u>Inner Surface Wave</u> $\omega = \left(-\frac{g}{R_1} R_1''\right)^{1/2}$ $M = \rho V$ $= \rho 4\pi R_1^2 \Delta R_{\text{pert.}}$ $\Delta R_{\text{pert.}} = R_1/l = H^{-1}$ $M = \rho 4\pi R_1^3/l$
-------------	---	---

∴ $S = \frac{1}{2} m \omega^2 L^2 A^2$

→ $\frac{1}{2} \frac{4\pi\rho R_1^3}{l} \left(-\frac{g}{R_1} R_1''\right)^{1/2} \eta^2$

= $\rho \frac{R_1^3}{l} \omega \eta^2$

$$\eta^2 \sim \frac{\sigma l}{\rho R_1^3 \omega} \sim \frac{\text{const.}}{R_1^{5/4} (\ddot{R}_1)^{1/2}}$$

$\eta \sim (\ddot{R}_1)^{-1/4} R_1^{-5/4}$
 \Rightarrow : perturbation grows by (x10) during coating phase!

References: K. O. Mikaelian; Phys. Rev. A 42 3400
 M. S. Plesset; J. Appl. Phys. 25 96 (1954)
 (*) D. L. Book, S. E. Bodner; Phys. Fl. 30 367 (1978)

b.) Analysis

i.) Coasting Shell "Equilibrium"

- Mass conserved during implosion

$$M = 4\pi \int_{R_1}^{R_2} \bar{\rho}(R) R^2 dr$$

$\bar{\rho} \equiv$ avg. density

$$= \frac{4\pi}{3} \bar{\rho} (R_2^3 - R_1^3)$$

$$= (4\pi/3) \bar{\rho} R_0^3$$

($R_0 \equiv$ radius fully collapsed shell)

- shell incompressible (ρ) - volume conserved

$$R^2 \dot{V} = R^2 \dot{R} = R_1^2 \dot{R}_1$$

$$\dot{R} = \frac{R_1^2 \dot{R}_1}{R^2}$$

- For total energy:

(K.E. of implosion)

$$W = \frac{1}{2} 4\pi \int_{R_1}^{R_2} \rho(R) R^2 dR \dot{R}^2$$

$$= 2\pi \int_{R_1}^{R_2} \bar{\rho} R^2 \frac{R_1^4}{R^4} \dot{R}_1^2 dR$$

$$W = 2\pi \bar{\rho} \dot{R}_1^2 R_1^3 (1 - R_1/R_2)$$

- time scale:

$$\tau_{\text{implosion}} = \left(M R_0^2 / 2W \right)^{1/2} \quad \left\{ \begin{array}{l} \text{mass} \\ \text{radius} \\ \text{energy} \end{array} \right.$$

- For \ddot{R}_1 (i.e. dynamics of implosion)

$$\dot{W} = 0 = 2\pi \bar{\rho} \left[3 \ddot{R}_1 R_1 \dot{R}_1 R_1^3 (1 - R_1/R_2) \right]$$

$$+ \dot{R}_1^2 (3 \dot{R}_1) (R_2^2) (1 - R_1/R_2) \\ + \dot{R}_1^2 R_1^3 \left(-\frac{\dot{R}_1}{R_2} + \frac{R_1 \dot{R}_2}{R_2^2} \right)]$$

with $R_2 \dot{R}_2 = R_1^2 \dot{R}_1$

(crank)

$$\Rightarrow \ddot{R}_1 = \frac{-W}{4\pi P R_1^4} \left[3 + 2 \frac{R_1}{R_2} + \left(\frac{R_1}{R_2} \right)^2 \right]$$

observe for $R_1 \ll R_2$ (thick shell limit)

$$\ddot{R}_1 \sim -\frac{C}{R_1^4}$$

$$R_1^2 \sim \frac{C}{R_1^3} \Rightarrow dR R_1^{3/2} \approx dt$$

$$R_1^{5/2} \sim (t_0 - t)$$

$$\Rightarrow R_1 \sim (t_0 - t)^{2/5}$$

↓
implosion radius evolution.

(2.) Perturbations (RT/SW)

- Take:
- rotational flow
 - incompressible hydro. $(\rho_0/R_1) \gg \left(-\frac{\ddot{R}_1}{R} \rho \right)''$

Then, as usual, have:

$$i.) \nabla^2 \phi = 0 \quad ; \quad \underline{V} = \nabla \phi$$

ii.) At interface \Rightarrow Bernoulli Eqn.:

$$\rho \left(\frac{\partial \phi}{\partial t} + \frac{(\nabla \phi)^2}{2} \right) + p = 0$$

here, unperturbed V from imploding shell

\Rightarrow

$$\frac{\partial \tilde{\phi}}{\partial t} + R \dot{\tilde{V}}_r + \tilde{p} = 0 \quad (1)$$

iii.) Boundary conditions at interfaces:

$$\frac{d\tilde{\eta}_j}{dt} = \tilde{V}_r + \left(\frac{\partial V}{\partial R} \right)_j \tilde{\eta}_j$$

\downarrow
shell expanding, here

$$\tilde{p}_j = - \left(\frac{\partial p}{\partial R} \right)_j \tilde{\eta}_j$$

\downarrow
shell expanding

but observe :

$$\rho \ddot{R} = -\frac{\partial P}{\partial R}$$

$$R^2 \dot{R} = R_j^2 \dot{R}_j = R^2 V$$

$$\begin{aligned} \therefore \left(\frac{\partial V}{\partial R} \right)_j &= \left[\frac{R_j^2 \dot{R}_j}{(R + \Delta R)^2} - \frac{R_j^2 \dot{R}_j}{R^2} \right] / \Delta R \\ &= -2 \frac{R_j \dot{R}_j}{R_j} \end{aligned}$$

$$\Rightarrow \boxed{\frac{d\tilde{\pi}_j}{dt} = \tilde{v}_j - 2 \frac{\dot{R}_j}{R_j} \tilde{\pi}_j} \quad (2)$$

$$\text{Similarly : } \boxed{\tilde{p}_j = \rho \ddot{R}_j \tilde{\pi}_j} \quad (3)$$

Now, to crack :

$$\nabla^2 \phi = 0 \Rightarrow$$

$$\phi(R, t) = \sum_{l,m} \left[R_1 v_1^{l,m}(t) \left(\frac{R_1}{R} \right)^{l+1} + R_2 v_2^{l,m}(t) \left(\frac{R}{R_2} \right)^l \right] * \gamma_{l,m}(\theta, \phi)$$

Then $\underline{v} = \underline{\nabla} \phi$

$$\underline{v}(R, t) = \sum_{\ell, m} \left[V_1 (R_1/R)^{\ell+2} \left[-\hat{r} (\ell+1) y_{\ell, m} + R \nabla y_{\ell, m} \right] + V_2 (R/R_2)^{\ell-1} \left[\hat{r} \ell y_{\ell, m} + R \nabla y_{\ell, m} \right] \right]$$

Substituting ϕ , $\nabla \phi$ into Bernoulli's Egn (ℓ^{th} mod)

$$\frac{-\rho}{\rho} = y_{\ell, m} \left[\left\{ R_1 \ddot{V}_1 + (\ell+2) \dot{R}_1 V_1 - (\ell+1) R_1 \dot{V}_1 \left(\frac{R_1}{R} \right) \right. \right. \\ \left. \left. * \left(\frac{R_1}{R} \right)^{\ell+1} + \left\{ R_2 \ddot{V}_2 - (\ell-1) \dot{R}_2 V_2 \right. \right. \right. \\ \left. \left. \left. + \ell R_2 \dot{V}_2 \left(\frac{R_2}{R} \right)^3 \right\} \left(\frac{R}{R_2} \right)^{\ell} \right] \right]$$

Further, taking \tilde{V}_r into Egn. (2) to relate $\dot{\eta}_1, V_1, V_2$:

$$\dot{\eta}_1 + 2 \left(\dot{R}_1 / R \right) \eta_1 = -(\ell+1) V_1 + \ell A^{\ell-1} V_2$$

$$\dot{\eta}_2 + 2 \left(\dot{R}_2 / R_2 \right) \eta_2 = -(\ell+1) A^{\ell+2} V_1 + \ell V_2$$

$$A = R_1 / R_2$$

Similarly, plugging (3) into Bernoulli Egn:

$$(R_1 \dot{V}_1 + [R_2 \dot{V}_2 + (\ell A^{-3} - \ell + 1) R_2 \dot{V}_2]) A^{\ell} = -\dot{R}_1 \eta_1$$

$$(R_1 \dot{V}_1 + [\ell + 2 - (\ell + 1) A^3] R_1 \dot{V}_1) A^{\ell+1} + (R_2 \dot{V}_2) = -\dot{R}_2 \eta_2$$

Now:

→ during coating phase, consider thick shell

$$R_1 / R_2 = A \ll 1 \Rightarrow \ell, A \rightarrow \infty$$

$$\rightarrow \eta_1 + 2 (R_1 / R_2) \eta_1 = -(\ell + 1) V_1$$

$$R_1 \dot{V}_1 = -\ddot{R}_1 \eta_1$$



$$\Rightarrow \left\{ \frac{d}{dt} \left(\frac{1}{R_1} \frac{d}{dt} (R_1^2 \tilde{\eta}_1) \right) = (\ell + 1) \ddot{R}_1 \tilde{\eta}_1 \right.$$

Similarly

$$\dot{\eta}_2 + 2(\dot{R}_2/R_2) \eta_2 = l V_2$$

$$\dot{V}_2 = -\frac{\ddot{R}_2}{R_2} \eta_2$$

$$\Rightarrow \boxed{\frac{d}{dt} \left(\frac{1}{R_2} \frac{d}{dt} (R_2^2 \eta_2) \right) = -l \frac{\ddot{R}_2}{R_2} \eta_2}$$

\Rightarrow two interfaces decouple !!

For inner interface (1):

\rightarrow coating shell $R_1 \sim (t_0 - t)^{2/5}$

$$\eta_1 \sim (t_0 - t)^\alpha \quad \text{and}$$

$$\frac{d}{dt} \left(\frac{1}{R_1} \frac{d}{dt} (R_1^2 \eta_1) \right) = (l+1) \frac{\ddot{R}_1}{R_1} \eta_1$$

$$\Rightarrow \alpha = \frac{-1}{10} \pm (25 - 24l)^{1/2}$$

$$\therefore \eta_1 \sim (t_0 - t)^{-1/10} \quad \left[\begin{array}{l} \text{slow increase} \\ \text{due to convergence} \end{array} \right]$$

note: consequence spherical convergence, not exponential growth.

> Wave-like solution (WKB)

$$\frac{d}{dt} \left(\frac{1}{R_1} \frac{d}{dt} (R_1^2 \tilde{\eta}_1) \right) = (\ell+1) \ddot{R}_1 \tilde{\eta}_1$$

$$\eta_1(t) = z(t) e^{i \int \omega(t') dt'}$$

$$-R_1 \omega^2 z + i (3\omega \dot{R}_1 z + 2\omega R_1 \dot{z} + \dot{\omega} R_1 z) + R_1 \ddot{z} + 3 \dot{R}_1 \dot{z} + 2 \ddot{R}_1 z = (\ell+1) \ddot{R}_1 z$$

lowest order: $\omega^2 = -\frac{\ddot{R}_1}{R_1} (\ell+1)$
→ eigen frequency

first order: $3\omega \dot{R}_1 z + 2\omega R_1 \dot{z} + \dot{\omega} R_1 z = 0$
 $\Rightarrow R_1^3 z^2 \omega = \text{const.}$

Recovers adiabatic invariant !!!
(SW Action, surface \odot) $\circ \circ$

Implications follow \circ

Note:

i) Question significant to Nova Upgrade \rightarrow advisability of long coasting phase

ii) Generally, for spherical R.T.:

$$\eta'' + 3 \frac{\dot{R}}{R} \eta' - n A(n) \frac{R''}{R} \eta = 0$$

$n \rightarrow 2$

$$n A(n) = \frac{[n(n-1) \rho_2 - (n+1)(n+2) \rho_1]}{[n \rho_2 + (n+1) \rho_1]}$$

need: $n A(n) R'' < 0$

$$\frac{d}{dt} [n A(n) R^5 R'] < 0$$

(P/ass et)

(HW)

10) Nonlinear Rayleigh-Taylor Instability: Single Mode / Bubble

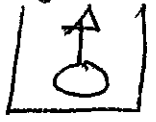
Ref. D. Layzer, Ap.J. 122 1 (1955). (a must)
H.J. Kull, Review

A.) Motivation and Heuristics

Recall;

i.) in linear phase, simple R.T. instability

$$\gamma = \sqrt{gAk} \quad (k\eta \ll 1)$$

ii.) in nonlinear phase, expect algebraic growth
(i.e. simple intuition) \rightarrow  bubble rise $z(t)$

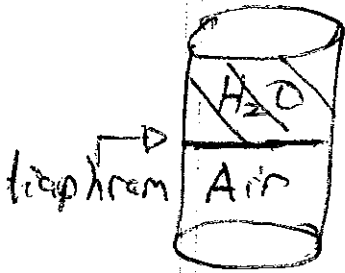
$$l = \alpha Ag t^2 \quad \left\{ \begin{array}{l} \text{light rises} \\ \text{etc bubble} \end{array} \right\} \quad (k\eta \gtrsim 1)$$

- Seek:
- \rightarrow how recover algebraic growth?
 - \rightarrow how unify linear, nonlinear regimes?
 - \rightarrow understand flow structure in nonlinear regime

Heuristically;

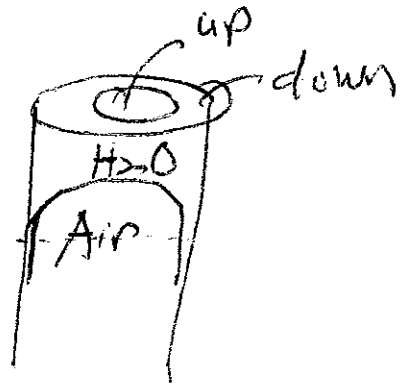
"NL": $\nabla \phi \cdot \nabla \eta \sim \frac{\partial \phi}{\partial z}$
 $\Rightarrow k \eta \sim 1$

then, for cylinder:



$A = 1$

\Rightarrow



i.e. air bubble rises in center
 $\left[\begin{array}{l} \text{H}_2\text{O spike falls at edge} \end{array} \right.$

\Rightarrow "spike and bubble" picture R, η

$\therefore \eta$ (interface variable) $\rightarrow R$ (bubble radius)
 (field, Fourier modes) (structure)

then, linear theory $\Rightarrow R \rightarrow l$

$$\gamma = \frac{1}{R} \frac{dR}{dt} = \sqrt{k g}$$

$$\frac{dR}{dt} = v = \sqrt{k R g R}$$

bubble rise velocity

1. natural to delineate:

① $kR = k\eta < 1$ - linear
 $\rightarrow R = R(0) e^{\gamma t}$

② $kR \geq 1$ $v = \sqrt{gR}$ - nonlinear

d.e $\frac{dR}{dt} = \sqrt{gR} \Rightarrow R = \alpha g t^2$

Suggests can understand nonlinear R.T. via notions of bubble dynamics!

B.) D. Lazer Calculation

Consider tube: $\left| \begin{array}{c} \text{H}_2\text{O} \\ \hline \text{air} \end{array} \right|_{z=0}$

tube radius



units: $R/\beta_1 = 1$

$g = 1$

$A = 1$

$J_1(r) \Big|_{r=\beta_1} = 0$

$r = \beta_1$
(first zero)

B.C's: Hard wall: $V_r(z, \beta_1, t) = 0$

$\Rightarrow \partial_r \phi(z, \beta_1, A) = 0$

Evanescent at top: $V_z(z, t) \Big|_{z \rightarrow \infty} = 0$

$\Rightarrow \partial_z \phi(z, t) \Big|_{z \rightarrow \infty} = 0$

Potential Flow: $\nabla^2 \phi = 0$

Approach to solution: \rightarrow How get/see 'spike and bubble' picture? shape-streamlines

\rightarrow convert interface dynamics problem into (nonlinear) particle mechanics problem

\rightarrow use fluid particle eqns. of motion to determine stream-lines, equation for boundary

Now, general solution to $\begin{cases} \text{Laplace eqn.} \\ \text{B.C.'s} \end{cases}$

$\phi = F(t) e^{-z} J_0(r)$
 \downarrow
 arbitrary fctn time

\rightarrow does not satisfy Bernoulli Eqn.

Then, for fluid particle:

$\frac{dx}{\partial_x \phi} = \frac{dy}{\partial_y \phi} = \frac{dz}{\partial_z \phi} \rightarrow$ equations for streamline

$$\frac{dr}{dt} = v_r = -\partial_r \phi$$

$$= +F(t) e^{-z} J_1(r)$$

$$\frac{dz}{dt} = v_z = -\partial_z \phi$$

$$= +F(t) e^{-z} J_0(r)$$

(Layzer notation)

exploits potential flow structure of problem \rightarrow obviously not universal applicable

Then, for stream-lines, can write:

$$dz/dr = v_z/v_r$$

$$= (dz/dt)/(dr/dt)$$

$$= J_0(r)/J_1(r)$$

but Bessel identity $\Rightarrow J_1'(r) = J_0(r) - \frac{J_1(r)}{r}$

$$\frac{dz}{dr} = \frac{J_1'(r) + J_1(r)/r}{J_1(r)}$$

$$= \frac{J_1'}{J_1} + \frac{1}{r}$$

$$dz = \frac{J_1'}{J_1} dr + \frac{dr}{r}$$

$$z = \ln(J_1(r)) + \ln r$$

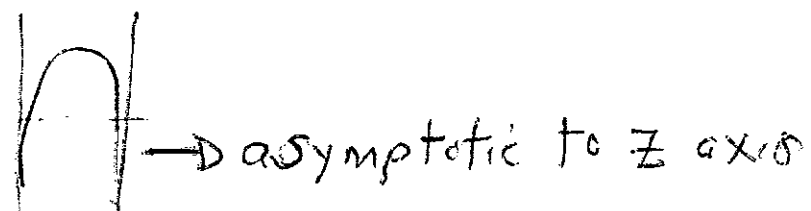
$$\Rightarrow \boxed{e^z = C r J_1(r)}$$

→ parametrizes fluid streamlines, if interface @ slightly distorted.
(no Bernoulli, yet)

Notes:

- generate stream surfaces via displacement along

\hat{z}
stream
- surfaces like:



$$\Rightarrow \text{i.e. } \left. e^{-|z|} \right|_{z \rightarrow -\infty} \approx \left. C r J_1(r) \right|_{r \rightarrow R}$$

⇒ streamline structure is underpinning (of spike + bubble intuition)

⇒ ~~not~~ not really solutions, but effect due to B.C. ^{artifact} (see 249)

Now, to obtain equation of motion for interface:

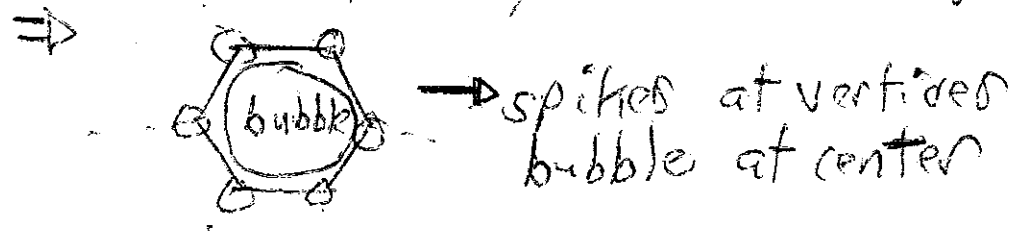
c.e.

→ solution not yet satisfy Bernoulli eqn \Leftrightarrow interface distortion
but

→ message is that B.C.'s force spike structure

c.e. $1 = \underbrace{C_n J_n(r)}_{\text{small}} \underbrace{e^{-z}}_{\text{large}}$

→ spike + bubble picture consequence $\left\{ \begin{array}{l} \text{B.C.'s} \\ \text{symmetry} \end{array} \right.$
c.p. hexagonal symmetry (cold convection)



(top view):

⇒ integrate fluid equations of motion:

$$\frac{dr}{dt} = + F(t) e^{-z} J_1(r) \quad \text{c.e.} \quad \frac{dx}{dt} = V$$

$$\frac{dz}{dt} = + F(t) e^{-z} J_0(r)$$

define: $Z = e^z$ → vertical variable

$V = r^2$ → radius

$T(t) = \int_0^t dt F(t) + 1$ → time variable

$k(v) = 2J_1(r)/r$ → shape

Now,

$$\frac{dZ}{dt} = \frac{dz}{dt} e^z = + F(t) J_0(r) \quad (\text{fluid eqns.})$$

$$= + F(t) J_0(\sqrt{V})$$

⇒

$$\frac{dZ}{dT} = J_0(\sqrt{V})$$

$$Z = V k(v) / (dV/dT)$$

→ plus.

and

Eliminating Z:

$$\frac{V}{V_0} = (T-1) \frac{k(V_0)}{Z_0 + 1} \quad \rightarrow \text{velocity}$$

$$\frac{Z}{Z_0} = \frac{k(V)}{k(V_0)} \left(\frac{(T-1) k(V_0)}{Z_0 + 1} \right)$$

Now:

→ potential can't solve Bernoulli eqn. over full surface

∴ → seek expansion valid near bubble vertex, i.e. weak distortion, see (26b.)

→ un-perturbed surface flat $\left\{ \begin{array}{l} V_0 = 0 \\ Z_0 = 1 \end{array} \right.$

$\left\{ \begin{array}{l} \text{flat surface} \\ \text{approximation} \end{array} \right. \leftarrow \text{---} \rightarrow \left\{ \begin{array}{l} r \approx 0 \\ \text{cylindrical} \end{array} \right.$

∴ neglecting non-linearities in v ($r \approx 0$)

⇒ $\frac{V}{V_0} = (T-1) \frac{k(V_0)}{Z_0 + 1} \quad \rightarrow \text{expansion}$

$$= (T-1) \frac{2V_0}{2}$$

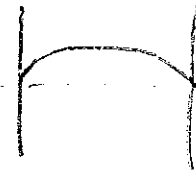
$$\therefore V = V_0 (T-1)$$

C.P.

→ unperturbed



→ weakly perturbed



→ strongly perturbed



$\Omega \approx 0$ approx.

↓
domain validity of
treatment shrinks as
bubble rises.

$$\eta' \sim Z$$

27.

Similarly: $e^{\eta'} = (T-1) \left[1 - \frac{V}{\delta} (1-T^{-2}) \right]$
 $Z \sim \ln(T), T \gg 1$

($\eta' \sim Z$)

$$\Rightarrow \begin{cases} V = V_0 (T-1) \\ e^{\eta'} = (T-1) \left[1 - \frac{V}{\delta} (1-T^{-2}) \right] \end{cases}$$

Then: $\phi = F(t) e^{-Z} J_0(r)$ into Bernoulli

$$\frac{\partial \phi}{\partial t} - (\nabla \phi)^2 \eta = 0$$

$$\Rightarrow \left\{ T(T^2+1) T'' - T'^2 - T^2(T^2-1) = 0 \right\}$$

i.e. $\rightarrow F \rightarrow T'$ (coeff. $V=0$)
 $\rightarrow \eta = \eta(T, V)$ (above)
 $\rightarrow \eta = \frac{d}{dt}$ (Bernoulli in real time)

Check:

a) Linear Regime (small time)

$$T = 1 + \tilde{T}, \quad \tilde{T} \ll 1$$

$$\Rightarrow (1+\tilde{T})((1+\tilde{T})^2+1) \tilde{T}'' - \tilde{T}'^2 - (1+\tilde{T})^2((1+\tilde{T})^2-1) = 0$$

$$\gamma'' - 2\gamma = 0$$

i.e. $\gamma = \gamma(0) e^{\gamma t} \rightarrow$ exponential growth
and linear theory.

In dimensional units:

$$\gamma = \gamma(0) e^{\gamma t}$$

$$\gamma = \sqrt{\frac{Rg}{\beta_1}}$$

$$\sim \sqrt{4g_{\text{eff}}}$$

\hookrightarrow set by cylindrical geometry

b.) Nonlinear Regimes $T \gg 1$

$$T^3 \gamma'' - \gamma^{3/2} - T^4 = 0$$

$$\gamma'' - \gamma = 0$$

$$\Rightarrow \gamma = e^{\gamma t} \Rightarrow \gamma' = F(t) = e^{\gamma t}$$

$V =$
Bubble
rise

$$\left. \frac{d\eta}{dt} \right|_{r=0} = \frac{d}{dt} \ln(T)$$

$$= \frac{1}{T} \frac{dT}{dt} = 1$$

(interface
eqn.)

$$\left[\begin{array}{l} e^{\eta} = (T-1) \quad (r \rightarrow 0) \\ \eta' e^{\eta} = \dot{\eta} \quad \eta \sim \ln T \\ T \gg 1 \end{array} \right.$$

Then $V = 1$, or in dimensional units:

$$V = \left(\frac{gR}{B_1} \right)^{1/2}$$

Agrees with free-fall in fact

c.) Can find general vertex dynamic solution

d.) $\left. \begin{array}{l} T \sim 1 \\ T \gg 1 \end{array} \right\}$ limits establish $k\eta \sim 1$
as criterion for entrance into nonlinear regime.

c.) Heuristics for Multiple Mode Systems

- Layer solution for single bubble/mode
- in reality, ICF target finnish irregularities initialize many modes

Seek: multi-mode criterion for non-linearity
 \Rightarrow amplitude for exponential growth
resonance ?!

ref: S. Haan, Phys. Rev. A 39 5812 (1989).

First, observe: all modes can't grow to $k \eta \sim 1$
 \Rightarrow spectral content diverges!

i.e.

$$\langle \xi^2 \rangle = \int dk k \tilde{\eta}^2$$

$$= \int k dk \frac{1}{k^2}$$

$\rightarrow \infty$

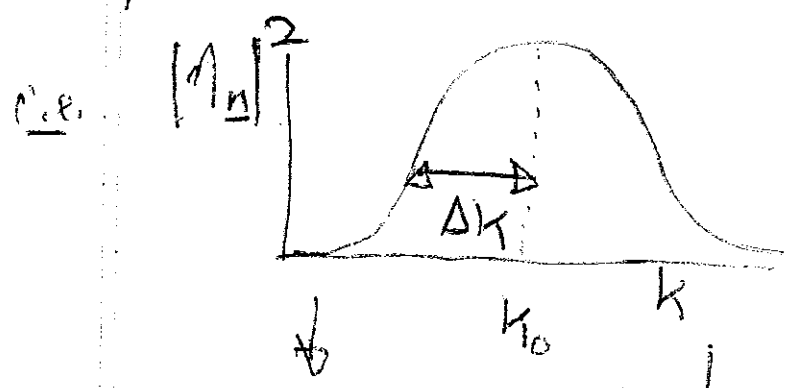
Some modes, especially long wavelength, remain in linear regime (slow)

natural, in multi-mode case, to suggest nonlinearity criterion $k \eta_{rms} \sim 1$, where

$k \eta_{rms}$ from superposition modes

k_0 refers to peak

wave number of spectra



spectrum \rightarrow peak + width

long wavelength modes grow slowly

ablation, k_0 cut-off

$$\begin{aligned} \therefore k_0^{-2} &= \frac{L^2}{(2\pi)^2} \int_0^{\infty} 2\pi k dk |\tilde{M}_k|^2 = \langle \tilde{M}^2 \rangle_{\text{ms}} \\ &= \frac{L^2}{2\pi} k_0 \Delta k |\tilde{M}_{k_0}|^2 \end{aligned}$$

⇒ establishes criterion:

$$M_{k_0} \approx \frac{\sqrt{2\pi}}{L} (k_0^3 \Delta k)^{-1/2}$$

if $\Delta k \sim k_0$ (frequent state affairs)

$$\Rightarrow \left\{ M_{k_0} \approx \frac{\sqrt{2\pi}}{L k_0^{+2}} \right. \quad \begin{array}{l} \text{contrast} \\ \text{to} \\ M_{k_0} \sim 1/k_0 \end{array}$$

↓
scaling with system!

→ in multimode system, superposition (bubble competition) of many-mode interface displacements ⇒ $k_0 M_{k_0} \approx \frac{\lambda_0}{L}$, not \perp (ala single wave)

→ transition to Layer regime at lower amplitude.

→ consistent with LLNL simulations, experiments

e) Bubble Competition and Mix \leftrightarrow Heuristics

\rightarrow goal is to:

- construct model of nonlinear Rayleigh-Taylor using Lazer spike + bubble model
- generate model of growth of mixing layer

\rightarrow ingredients:

∇ single bubble model

- bubble - bubble interaction \Rightarrow Competition

A) Single Bubble

- Lazer calculation \Rightarrow bubble vertex rises at $V = (gR/\beta_1)^{1/2}$

\therefore suggests that mixing layer grows as:

$$\frac{dl}{dt} = (gl)^{1/2} \quad l \sim \alpha g t^2$$

out

omits other effects which limit bubble/spike dynamics:

→ compression

→ drag, spike KH

1D Model: $\begin{cases} v(l, z, t) \rightarrow \text{bubble rise velocity} \\ l(z, t) \rightarrow \text{mixing layer width} \end{cases}$ (z)

bubble compression \downarrow \rightarrow bubble rise velocity $\sim (gl)^{1/2}$

$$\frac{\partial l}{\partial t} + v \frac{\partial l}{\partial z} = v$$

$$\rho \frac{\partial v}{\partial t} = \rho g - \rho C_D \frac{v^2}{l} \rightarrow \underline{\text{drag}}$$

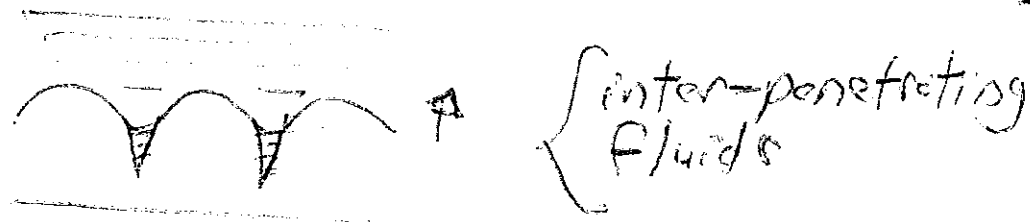
\downarrow
gravitational
force

(D. Youngs
Physics A 37 (198)
270
+ refs therein)

Physics of Drag:

- view bubble rise as mixture of two inter-penetrating fluids:

i.e.,



→ drag coefficient (phenomenological)

$$Fo = C_D \frac{V}{f} \rho V$$

momentum

time scale ($l \leftrightarrow$ "chunk" size for interpenetrating fluids)

Drag slows bubble rise

i.e.,

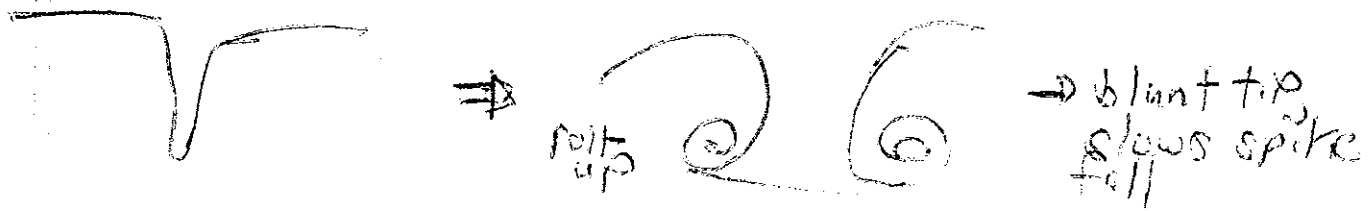
$$\frac{dV}{dt} = 0 \Rightarrow V = \left(\frac{1}{C_D}\right)^{1/2} (g l)^{1/2}$$

$$l = C_D^{-1/2} \frac{g}{\Sigma} f^2$$

∴ Drag coefficient contains physics of $\alpha \sim 0.5$ scaling!

- alternatively, view drag term as manifestation of decay due to spike shear flow instability

i.e.,
recall:



Now time scale for roll-up is flow shear rate,

i.e. $\gamma \sim |\nabla u|$

∴ dimensionally, $\gamma \sim \frac{V}{l} \Rightarrow$ rate of drag.

⇒ drag {term coefficient} essential to proper fit of implosion experiment data.

B.) Bubble Competition

observe:

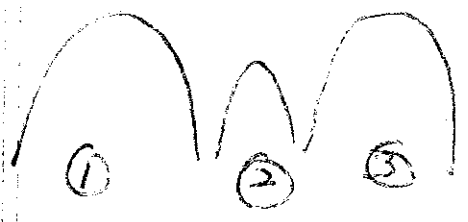
- single bubble mixing model characterized by single length scale

but

- multi-mode system \Rightarrow multi-bubbles

∴
- need describe trend in evolution of bubble length scale

simple example:



t

3 bubbles
exterior larger

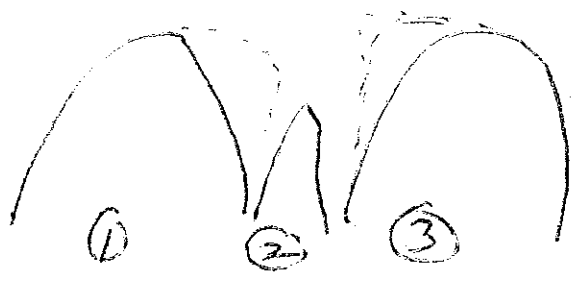
$$l_2 < l_1, l_3$$

→ but, in Lazer regime:

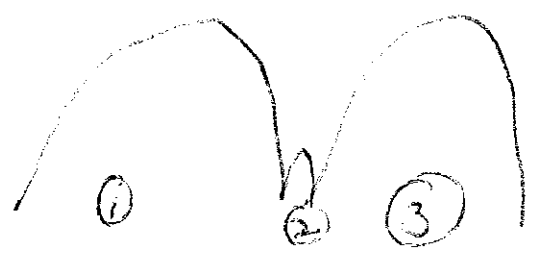
$$v \sim (gl)^{1/2}$$

⇒ larger bubbles rise faster

→ ∴, at $t + \Delta t$



⇒ ① ③ will tend to expand over ②, thus "squeezing" it out



→ trend in bubble competition is:

- larger bubbles rise faster
- squeeze out smaller bubbles

⇒ trend is progression towards single length scale characteristic of largest bubble
 ⇒ soon as "inverse cascade".

→ can build multi-bubble Lazer model (2D with discrete dynamics in z).

Ph 5105 2/8A

P. Diamond

Bubble, Bubble, Toil and Trouble ...

Last time:

→ discussed D. Lazer (SS) solution for single, nonlinear bubble.

- why: observables in NL state
 $\gamma'(1\text{cm}) \sim 0.1 \text{ sec.}$

- what: → single mode ($\lambda \approx R$) growth
 in $\left\{ \begin{array}{l} k\eta \sim 1 \\ \ell \rightarrow \infty \end{array} \right. \left(\eta/R \sim 1 \right)$ regime
 i.e. $V = \#(gR)^{1/2}$

→ connects exponential and algebraic growth regimes (NL saturation)

- how: → flat interface approximation at
 (i.e. $\Gamma \rightarrow 0$) \Leftrightarrow geometry
 bubble tip.

→ use of streamlines from $\nabla^2 \phi = 0$
 and (assumed) self-similarity (valid at bubble tip).

→ Today:

- (i) Lazy Man's Layer
- (ii) Bubble Competition

I.) Recall basic R-T equations:

$$- \nabla^2 \phi = 0$$


$$- \frac{\partial \eta}{\partial t} + \underline{\nabla} \phi \cdot \underline{\nabla} \eta = V_z \quad \underline{\underline{0 \text{ or } \infty}}, \text{ more generally,}$$

"interface moves with fluid"

$$- \frac{\partial \phi}{\partial t} + \underline{\nabla} \phi \cdot \underline{\nabla} \phi + g \eta = \text{const.}$$

For single mode (bubble):

$$\phi(x, z, t) = a(t) \cos(kx) e^{-kz}$$

 → since bubble is rising light fluid, bubble flow must vanish at $+\infty$.

Now, essence of Layer / bubble tip approximation is geometric → assumed shape of bubble, i.e.:

$$z_c(x, t) = \eta(x, t) = z_0 + z_1 (x - x_c)^2$$

c.e. parabolic shape approximation:

$x_i, z_0 \rightarrow$ tip location

$z_1 \rightarrow$ radius of curvature of bubble
c.e. $R_c = -1/2z_1$

Note: Linear: $\gamma \vec{n} = \frac{\partial \tilde{\phi}}{\partial z}$
c.e. $\tilde{\phi}$ forces η
Lagzer: $\eta \leftrightarrow$ geometry

Then:

$$\eta = z = z_0 + z_1 (x - x_i)^2$$

$$\frac{\partial \eta}{\partial t} + \underline{v} \cdot \underline{\nabla} \eta = \frac{\partial \phi}{\partial z}$$

$$\Rightarrow \frac{dz_0}{dt} + (x - x_i)^2 \frac{dz_1}{dt} + (-2)z_1 (x - x_i) \frac{dx_i}{dt}$$

$$+ v_x 2(x - x_i) = v_z$$

$$\Rightarrow V_z - \frac{dz_0}{dt} - \frac{dz_1}{dt} (x-x_1)^2 - 2z_1 (x-x_1) \left(V_x - \frac{dx_1}{dt} \right) = 0$$

∴ we have:

$$\phi = a(t) \cos(kx) e^{-kz} \quad ; \quad \underline{V} = \underline{\nabla} \phi$$

①
②
③
↓

$$V_z - \frac{dz_0}{dt} - \frac{dz_1}{dt} (x-x_1)^2 = -2z_1 (x-x_1) \left(V_x - \frac{dx_1}{dt} \right)$$

} interface eqn.

and

$$\frac{\partial \phi}{\partial t} + \frac{V_x^2 + V_z^2}{2} + g z = \text{const.}$$

Plugging in, to 2nd order:

Interface eqn: $O(d)$;

$$-ka(t) \cos(kx) \Big|_{x=0} e^{-kz_0} - \frac{dz_0}{dt} = 0$$

1 (t.p)

$$\Rightarrow \left\{ a k e^{-kz_0} + \frac{dz_0}{dt} = 0 \right.$$

to O(2):

$$\left\{ a k^2 \left(z_1 + \frac{k}{2} \right) e^{-kz_0} - \frac{dz_1}{dt} + 2z_1 a k^2 e^{-kz_0} = 0 \right.$$

and Bernoulli (to O(2)):

$$\begin{aligned} & \downarrow \partial \phi / \partial t \\ & k e^{-kz_0} \left(z_1 + \frac{k}{2} \right) \frac{da}{dt} + a^2 \underbrace{k^3}_{\sqrt{2}} z_1 e^{-2kz_0} \\ & - g z_1 = 0 \end{aligned}$$

Recall: $\rightarrow e^{-kz}$

$$\downarrow z_0 + z_1 (x - x^2)$$

#w.

\rightarrow bubble tip ($x \rightarrow 0$)

\Rightarrow equiv. Loyer solution.

Check: linear solution:

$$\frac{k}{2} e^{-kz_0} \frac{da}{dt} = g z_1$$

$$\frac{ak^3}{2} e^{-kz_0} = \frac{dz_1}{dt}$$

so, small perturbations \Rightarrow

$$\frac{k^2}{2} e^{-kz_0} \frac{da^2}{dt} = \frac{g a k^3}{2}$$

$$\frac{da^2}{dt^2} = g k a \quad \checkmark \text{ etc.}$$

low, for late times:

$$k e^{-kz_0} \left(z_1 + \frac{k}{2} \right) \frac{da}{dt} + a^2 k^3 z_1 e^{-2kz_0} = g z_1$$

mode sets,

$$\left\{ \begin{array}{l} v^2 \sim gM \sim g\lambda \\ \text{balance} \end{array} \right.$$

$$\Rightarrow a^2 k^3 \sim g$$

$$(ka)^2 \sim g/k \quad \Rightarrow \quad v^2 \sim g\lambda$$

$$\text{akin } v^2 \sim (gR)$$

etc.

→ what's important?

① → birth/death structure

② → self-similarity (i.e. all N -coagulated

③ → same merger rules.

① - ③ ⇒ inverse cascade.

More general form :

$$N(t) \frac{\partial g(\lambda, t)}{\partial t} = -2g(\lambda, t) \int_0^\infty g(\lambda', t) w(\lambda, \lambda') d\lambda' \quad \downarrow \text{death}$$

$$+ \int_0^\lambda g(\lambda - \lambda', t) g(\lambda', t) w(\lambda - \lambda', \lambda) d\lambda' \quad \uparrow \text{birth}$$

$$N = \int_0^\infty g(\lambda, t) d\lambda \equiv \# \text{ bubbles at } t$$

$g(\lambda, t) d\lambda$ = size distribution function

$w(\lambda_i, \lambda_{i+1}, t)$ → merger rate

